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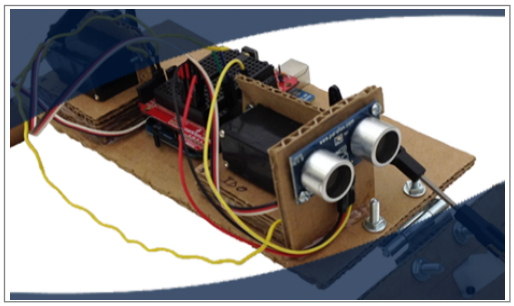

Control of Mobile Robots

This course investigates control design for mobile robots, including topics such as dynamical systems, state-space based control design, nonlinear and hybrid robot models, and advanced navigation strategies.

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